

Automatic Discovery of Partial Differential Equation Models from Broadly Spaced Data

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INTRODUCTION

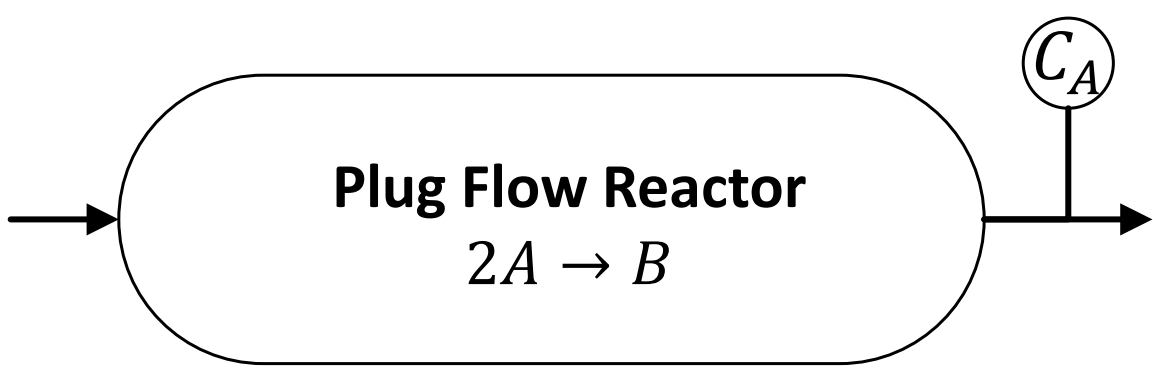
PARTIAL DIFFERENTIAL EQUATIONS (PDES)

- Predict State Variable in time and space
- Explain changes in time and space
- Discover PDE models from data when space between measurements is small

$\frac{\partial u}{\partial t}$	$\frac{\partial u}{\partial z}$	$\frac{\partial^2 u}{\partial z^2}$	$\left(\frac{\partial V}{\partial T}\right)_P$	$\left(\frac{\partial V}{\partial P}\right)_T$
Dynamics	Convection	Diffusion	Thermal Expansivity	Isothermal Compressibility

BROADLY SPACED DATA

- Spacing sensors frequently may be difficult or expensive
- Measuring chemical species is often done at the outlet of a reactor



OPPORTUNITY

Create partial differential equation models from broadly spaced measurements

RECOVER UNKNOWN PHYSICS FROM DATA

CHEMICAL REACTOR PHYSICS

$$\frac{\partial C_A}{\partial t} = s \left(C_A, \frac{\partial C_A}{\partial z}, \frac{\partial^2 C_A}{\partial z^2}, v, C_{A,f} \right)$$

PHYSICS

- Dynamics: $\frac{\partial C_A}{\partial t}$
- Reaction: θC_A^ϕ
- Convection: $\theta \frac{\partial C_A}{\partial z}$
- Diffusion: $\theta \frac{\partial^2 C_A}{\partial z^2}$

CONTROLS

- Flow Velocity: θv
- Feed Concentration: $\theta C_{A,f}$
- Initial Condition: $C_A = 0$ at $t = 0$
- Inlet Condition: $C_A = C_{A,f}$ at $z = 0$
- Outlet Condition: $\frac{\partial C_A}{\partial z} = 0$ at $z = l$

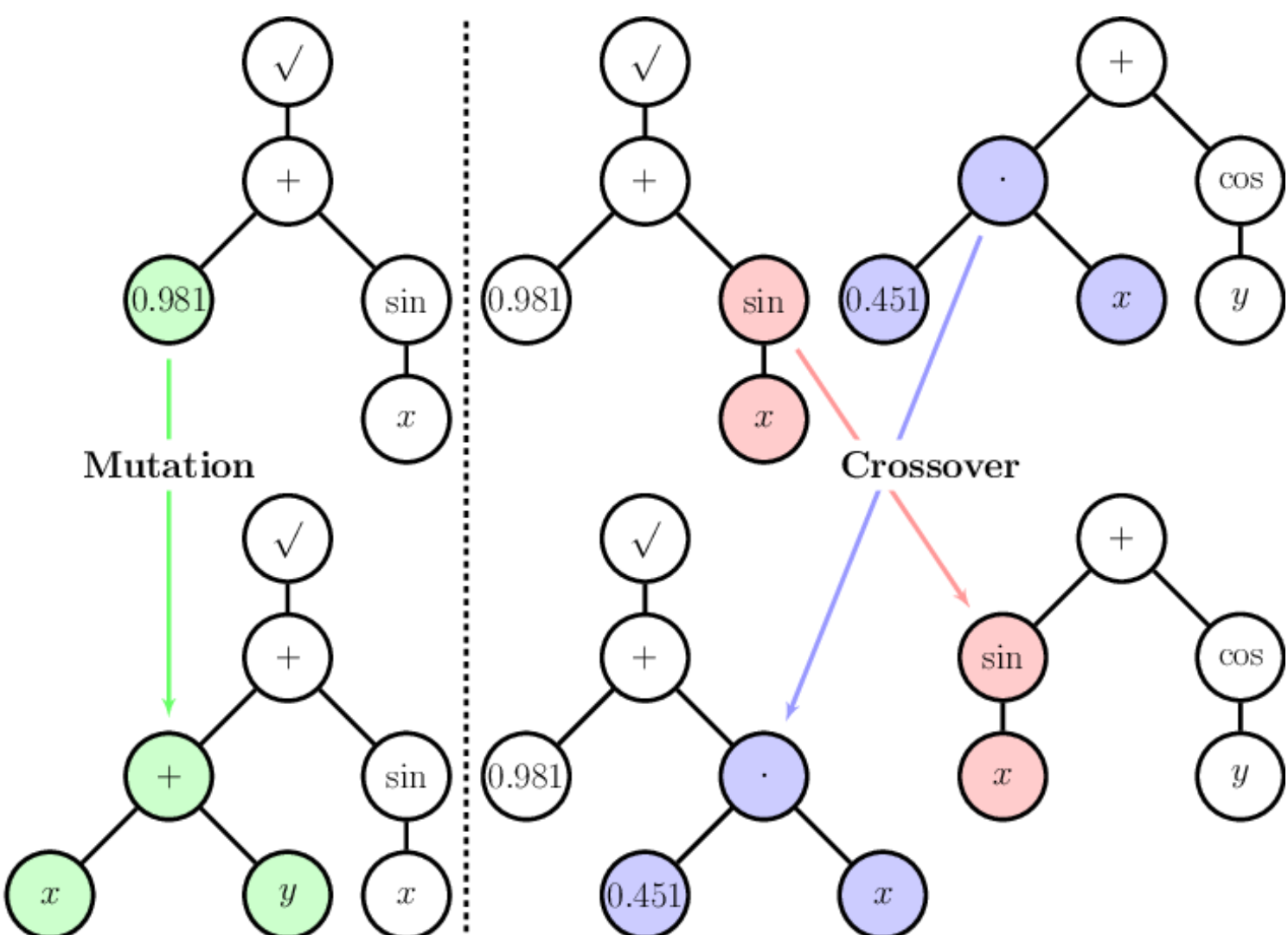
SYMBOLIC REGRESSION VIA GENETIC PROGRAMMING

Symbolic Regression

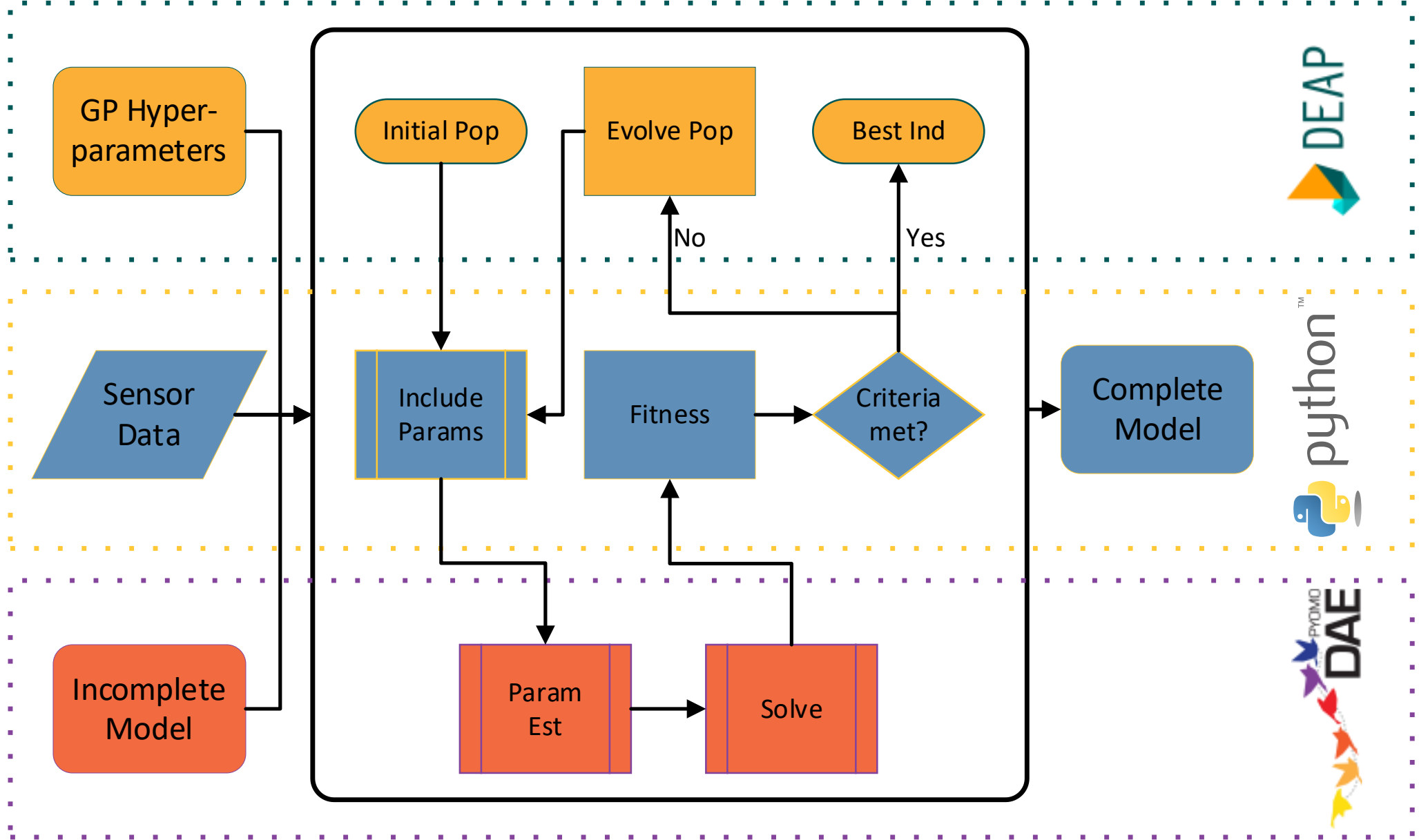
- Discover model shape
- Physics-informed
- Data-driven
- Identify parameters

Genetic Programming

- Inspired by evolution
- Mutation
- Cross-over



FRAMEWORK



$$s^* \in \arg \min_{s \in S} I(s)$$

$$s, t.$$

$$\theta^* \in \arg \min_{\theta \in \mathbb{R}} \frac{1}{t_f} \int_0^{t_f} (\hat{C}_A - C_{A,meas}) dt$$

$$s, t.$$

$$\frac{\partial C_A}{\partial t} - s = 0$$

$$C_A = 0 \text{ at } t = 0$$

$$C_A = C_{A,f} \text{ at } z = 0$$

$$\frac{\partial C_A}{\partial z} = 0 \text{ at } z = l$$

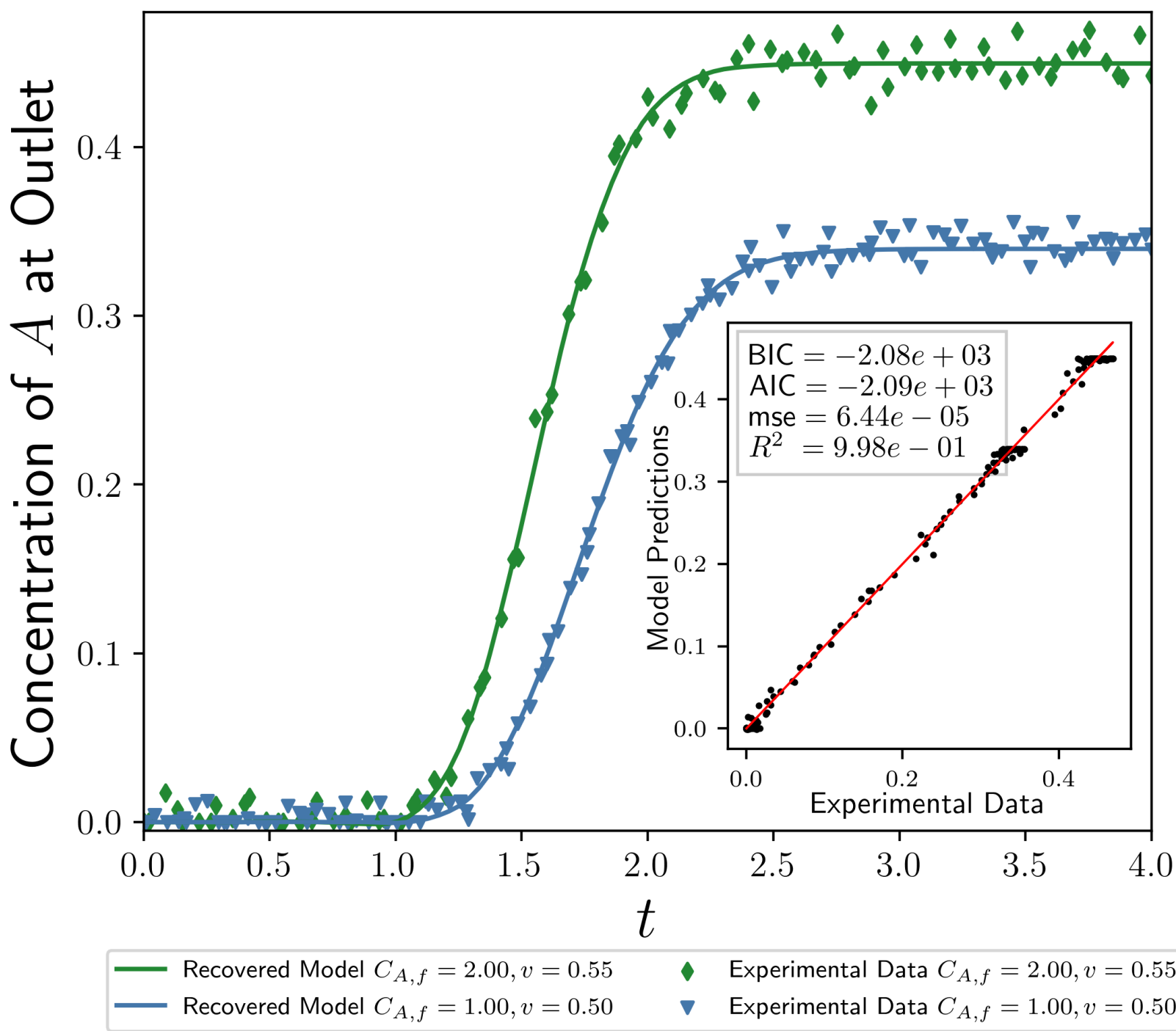
$$t \in [0, t_f], z \in [0, l]$$

- Minimize Information Theoretic Criterion, $I(s)$
- Find least complex model that agrees with data
- Gradient-based parameter estimation scheme

RESULTS

PLUG FLOW REACTOR (PFR)

$$\frac{\partial C_A}{\partial t} = 0.01 \frac{\partial^2 C_A}{\partial z^2} - 1.00v \frac{\partial C_A}{\partial z} - 1.00C_A^{2.00}$$
$$\frac{\partial C_A}{\partial t} = 0.01 \frac{\partial^2 C_A}{\partial z^2} - 1.00v \frac{\partial C_A}{\partial z} - 1.02C_A^{1.95}$$



- Successfully recovered model structure and parameters
- No predefined combinations of argument set terms

CONCLUSIONS AND FUTURE WORK

CONCLUSIONS

- Framework can recover simple PDE models
- Framework can discard terms from argument set
- Framework does not need predefined combinations of terms

FUTURE WORK

- Increase system model complexity (non-isothermal reactors)
- Leverage information theory for optimal design of experiments

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